

Standard KD-based Class Incremental Learning

Class incremental learning

Learning tasks arrive in a sequence and deep neural network θ must continually learn to increment already acquired knowledge.

Rehearsal method

Store a subset of previous samples M_t , and train them together with samples of a new task D_t to prevent forgetting previous knowledge.

Knowledge Distillation based method

Try to mitigate forgetting by transferring the previous knowledge distilled from the pre-trained model.

Standard KD-based Method loss function

$$\lambda \mathcal{L}_{kd}(\mathcal{D}_t \cup \mathcal{M}_t, \Theta_t) + (1 - \lambda) \mathcal{L}_{ce}(\mathcal{D}_t \cup \mathcal{M}_t, \Theta_t)$$

$$\mathcal{L}_{kd}(\mathcal{D}, \Theta) = - \sum_{(\mathbf{x}, \mathbf{y}) \in \mathcal{D}} \hat{q}(\mathbf{x}) \log q(\mathbf{x}) \quad \mathcal{L}_{ce}(\mathcal{D}, \Theta) = - \sum_{(\mathbf{x}, \mathbf{y}) \in \mathcal{D}} \mathbf{y} \log p(\mathbf{x})$$

Softened probability (reference model) Softened probability Softmax probability

Motivation

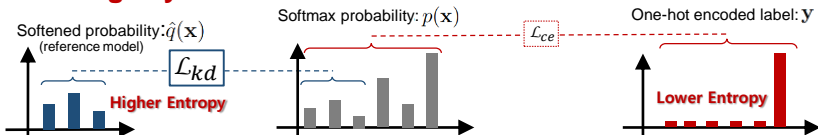
- Our observation:** we can think of class incremental learning as the problem of learning 3 types of knowledge.

Intra-old / Intra-new / Cross-task

- We can further identify **which part of the loss function is utilized** to acquire each type of knowledge in Standard KD-based method.

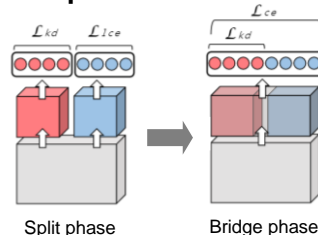
- Intra-old knowledge: $\mathcal{L}_{kd}(\mathcal{D}_t \cup \mathcal{M}_t, \Theta_t) + \mathcal{L}_{ce}(\mathcal{M}_t, \Theta_t)$
- Intra-new knowledge: $\mathcal{L}_{ce}(\mathcal{D}_t, \Theta_t)$
- Cross-task knowledge: $\mathcal{L}_{ce}(\mathcal{D}_t \cup \mathcal{M}_t, \Theta_t)$

- KD-based method **suffer from learning intra-new and cross-task knowledge by CE loss**



Overview

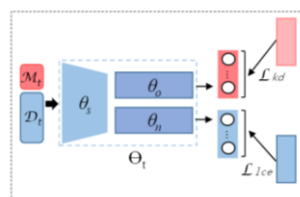
- We propose a two phase learning method within a single network to learn **without any competition between losses**



Proposed Adaptable Incremental Learning

Separated learning within a single network

To learn the intra-new knowledge as independently as possible from the task of preserving the intra-old knowledge.



Separated partition: Old partition
 $\Theta_t \rightarrow \langle \theta_s, [\theta_o, \theta_n] \rangle_t$
 New partition

Loss function:

$$\mathcal{L}_{kd}(\mathcal{D}_t \cup \mathcal{M}_t, \langle \theta_s, \theta_o \rangle_t) + \mathcal{L}_{lce}(\mathcal{D}_t, \langle \theta_s, \theta_n \rangle_t)$$

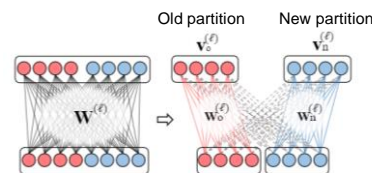
Localized Cross Entropy:

$$\mathcal{L}_{lce}(\mathcal{D}_t, \Theta) = - \sum_{(\mathbf{x}, \mathbf{y}) \in \mathcal{D}_t} \mathbf{y}_t \log p_t(\mathbf{x})$$

Local Softmax probability

Weight sparsification across tasks

We gradually remove inter-connected weights $W_{o,n}$ and $W_{n,o}$ to get a separated network with less previous knowledge loss.

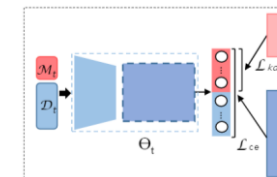


Loss function:

$$\mathcal{L}_{kd}(\mathcal{D}_t \cup \mathcal{M}_t, \Theta_t) + \mathcal{L}_{lce}(\mathcal{D}_t, \Theta_t) + \gamma \sum_{\ell=S+1}^L (\|W_{o,n}^{(\ell)}\|_2 + \|W_{n,o}^{(\ell)}\|_2)$$

Bridge phase

We re-connect two partitions θ_o and θ_n in order to learn the cross-task knowledge between them.



Re-connect separated partitions:

$$\langle \theta_s, [\theta_o, \theta_n] \rangle_t \rightarrow \Theta_t$$

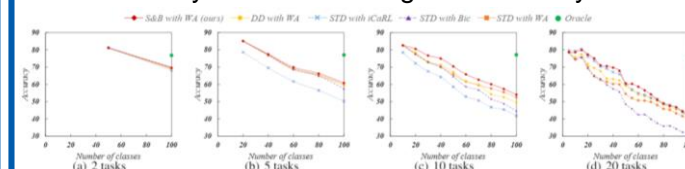
connect through zero-initialized weight

$$\lambda \mathcal{L}_{kd}(\mathcal{D}_t \cup \mathcal{M}_t, \Theta_t) + (1 - \lambda) \mathcal{L}_{ce}(\mathcal{D}_t \cup \mathcal{M}_t, \Theta_t)$$

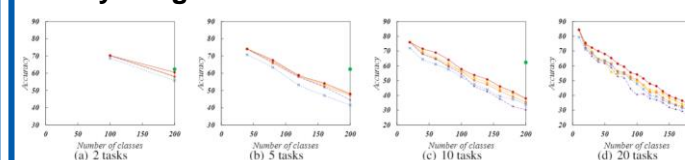
Experimental Results

CIFAR-100 in ResNet-18

consistently achieves the highest accuracy



Tiny-ImageNet in ResNet-18 (highest accuracy)



Average intra-new and intra-old accuracy

highest intra-new accuracy & preserving intra-old accuracy

